BASIN DRILLING, LP RIG #103

DRAWWORKS:

Gardner Denver 1500-E (2000HP)

(2) GE 752 Standard-Torque drilling DC drilling motors, NOV Baylor 7838 auxiliary brake

POWER:

(4) Caterpillar 399-B engines (1200HP each) with Kato 1030 KW AC synchronous generators

SCR SYSTEM:

International Electric Company Systems (IPS) 4x4 (2000HP) SCR house w/ GE evolution 9000 MCC

MAST:

Superior Derricks 142' w/ 1,000,000# capacity on 12 lines

SUBSTRUCTURE:

26' Superior box-on-box substructure 1,000,000# rotary table supporting capacity 800,000# pipe setback load capacity

WALKING SYSTEM:

OWI Stealthwalker multidirectional rig walking system.

BLOCK HOOK:

National G-650 650 ton w/ becket

PUMPS:

(2) HHF-1600 (1600HP) triplex pumps powered by (2) GE 752 traction motors w/ 7500 psi fluid ends

MUD PITS

(3) tank system – 1600 bbl w/ 70 bbl slug pit

SOLIDS EQUIPMENT:

- (3) Derrick Hyperpool shale shakers
- (1) Derrick 2-cone desander
- (1) Derrick 16-cone desilter
- (7) mud agitators
- (1) Derrick vacuum degasser
- (1) 4' x 20' mud gas separator

BOP'S:

13 % " x 5,000 psi Hydril GL Annular

13 % " x 10,000 psi Cameron Type U double

13 % " x 10,000 psi Cameron Type U single

ACCUMULATOR:

CPC 10 station accumulator

CHOKE MANIFOLD:

10,000 psi choke manifold

TOP DRIVE:

CANRIG 1250AC-681 (500 ton)

- -1150 hp AC Electric Drive
- -7500 psi integrated swivel
- -Max Drilling Torque = 51,400 ft-lb
- -Max Breakout Torque = 95,000 ft-lb
- -Maximum Speed = 265 rpm
- -Rockit & Revit compatible

ROTARY TABLE:

National $(49 \frac{1}{2})$ w/ $(37 \frac{1}{2})$ insert bushings

PIPE HANDLING:

NOV ST-80 Iron Roughneck NOV PipeCat laydown system

DRILL PIPE:

5" 19.50# S-135 NC-50 drill pipe

DRILL COLLARS:

8" Round Drill Collars 6 ½" Spiral Drill Collars

AUXILIARY EQUIPMENT:

PASON EDR (base system)

Fuel Tank – 10,500 gallon capacity

Water Tank – 500 bbl capacity

Rig Manager and Crew Quarters

(2) air hoists (10,000# capacity each)

Electronic survey unit w/ 15,000' wireline machine

Drill pipe spinner

Top drive Supervisor